

Feuille 4

exercice 1:

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$d_a f: \underset{\substack{\uparrow \\ \text{(direction)}}}{h} \mapsto \nabla_a f \times h$$

\uparrow
 \mathbb{R}^n

$$\nabla_a f \left(\frac{\partial f}{\partial x_1}(a), \dots, \frac{\partial f}{\partial x_n}(a) \right)$$

$$\bullet \frac{\partial f}{\partial x}(x_0, y_0) = y_0$$

$$\bullet \frac{\partial f}{\partial y}(x_0, y_0) = x_0$$

$$d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} f : (h_1, h_2) \mapsto \nabla_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} f \times \begin{pmatrix} h_1 \\ h_2 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} g & x_0 \end{pmatrix} \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} := g h_1 + x_0 h_2$$

done : $d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} f : (h_1, h_2) \mapsto g h_1 + x_0 h_2$

$$\bullet g(x, y) = \left(\underbrace{g_1(x, y)}_{x+y} ; \underbrace{g_2(x, y)}_{xy} \right)$$

$$\nabla_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} f \left(\begin{array}{cc} \frac{\partial g_1(x_0, y_0)}{\partial x} & \frac{\partial g_1(x_0, y_0)}{\partial y} \\ \frac{\partial g_2(x_0, y_0)}{\partial x} & \frac{\partial g_2(x_0, y_0)}{\partial y} \end{array} \right)$$

$$f: \mathbb{R}^n \longrightarrow \mathbb{R}^p$$

$$(x_1, \dots, x_n) \longmapsto (f_1, \dots, f_p)$$

$J_a f$

$$\begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \dots & \frac{\partial f_1}{\partial x_n}(a) \\ \vdots & & \vdots \\ \frac{\partial f_p}{\partial x_1}(a) & \dots & \frac{\partial f_p}{\partial x_n}(a) \end{pmatrix}$$

taille $p \times n$

$$J_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} g \begin{pmatrix} 1 & 1 \\ y_0 & x_0 \end{pmatrix}$$

$$d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} g : (h_1, h_2) \mapsto \underbrace{J_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} g}^* \begin{pmatrix} h_1 \\ h_2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ y_0 & x_0 \end{pmatrix} \begin{pmatrix} h_1 \\ h_2 \end{pmatrix} = \begin{pmatrix} h_1 + h_2 \\ y_0 h_1 + x_0 h_2 \end{pmatrix}$$

done :

$$d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} g : (h_1, h_2) \mapsto \begin{pmatrix} h_1 + h_2 \\ y_0 h_1 + x_0 h_2 \end{pmatrix}.$$

$$d_a (f \circ g) = d_{g(a)} f \circ d_a g$$

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$$J_a (f \circ g) = J_{g(a)} f \times J_a g$$

$$d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} (f \circ g) = d_{g(x_0, y_0)} f \circ d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} g$$

$(g_1(x_0, y_0); g_2(x_0, y_0))$

$$\text{or } d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} f(h_1, h_2) = h_1 g_1 + h_2 g_2$$

$$d'_{a\bar{a}} \quad d_{g(x_0, y_0)} f(h_1, h_2) = h_1 g_1(x_0, y_0) + h_2 g_2(x_0, y_0)$$

$$= h_1 x_0 y_0 + h_2 (x_0 + y_0)$$

on va prendre
$$\begin{cases} h_1 = h_1 + h_2 \\ h_2 = y_0 h_1 + x_0 h_2 \end{cases}$$

Donc :

$$\begin{aligned} d_{\begin{pmatrix} x_0 \\ y_0 \end{pmatrix}} (f \circ g)(h_1, h_2) &= (h_1 + h_2) x_0 y_0 + (y_0 h_1 + x_0 h_2) \times (x_0 + y_0) \\ &= h_1 x_0 y_0 + h_2 x_0 y_0 + x_0 y_0 h_1 + y_0^2 h_1 \\ &\quad + x_0^2 h_2 + x_0 y_0 h_2 \\ &= x_0^2 h_2 + y_0^2 h_1 + 2x_0 y_0 h_1 + 2x_0 y_0 h_2 \end{aligned}$$

$$\begin{aligned} (f \circ g)(x, y) &= f(x+y, xy) \\ &= (x+y)xy = x^2 y + xy^2 \end{aligned}$$

exercice 3:

$$1) g_u(t) = f(x_0 + tu)$$

Comme f est différentiable au point x_0 , alors il existe une application linéaire $d_{x_0}f$ telle que, pour tout $h \in \mathbb{R}^n$.

$$f(x_0 + h) = f(x_0) + d_{x_0}f(h) + o(\|h\|)_{h \rightarrow 0}$$

on prend $h = tu \in \mathbb{R}^n$.

$$f(x_0 + tu) = f(x_0) + d_{x_0}f(tu) + o(\|tu\|)_{t \rightarrow 0}$$

$$g_u(t) = f(x_0) + t d_{x_0}f(u) + o(\|t\|\|u\|)_{t \rightarrow 0}$$

$$g_u(t) = g_u(0) + t d_{x_0}f(u) + o(\|t\|)_{t \rightarrow 0}$$

$$\text{d'au} \quad \frac{g_u(t) - g_u(0)}{t - 0}$$

$$= d_{x_0} f(u) + o(1)$$

$$\text{donc } \lim_{t \rightarrow 0} \frac{g_u(t) - g_u(0)}{t - 0} = d_{x_0} f(u)$$

Ainsi g est dérivable en $t = 0$ et $g'_u(0) = d_{x_0} f(u)$

$$2) \quad g_u(t) = f(tu)$$

$$= f(tu_1, tu_2)$$

$$= \frac{(tu_1)^2 \times tu_2}{(tu_1)^2 + (tu_2)^2}$$

$$= \frac{t^3 u_1^2 u_2}{t^2 u_1^2 + t^2 u_2^2}$$

$$= \frac{t^2 (t u_1^2 u_2)}{t^2 (u_1^2 + u_2^2)}$$

$$= t \times \frac{u_1^2 u_2}{u_1^2 + u_2^2}, \quad (u_1, u_2) \neq (0, 0)$$

Donc $g'_u(t) = \frac{u_1^2 u_2}{u_1^2 + u_2^2}, \quad u \neq 0$

et $g'_u(0) = \frac{u_1^2 u_2}{u_1^2 + u_2^2}, \quad u \neq 0$

si $u = 0$, $g_0(t) = f(0, 0) = 0$

ainsi

$$g'_u(0) = 0$$

• Si f est différentiable en $(0,0)$, alors d'après la question 1 on aurait que :

$$g'_u(0) = d_{(0,0)} f(u)$$

et $u \mapsto g'_u(0)$ doit être linéaire.

$$g'_{(1,0)}(0) = 0$$

$$g'_{(0,1)}(0) = 0$$

$$\text{or } g'_{(1,1)}(0) = 1 \neq 0 + 0$$

$(1,0) + (0,1)$

donc $g'_u(0)$ n'est pas
linéaire et donc f n'est
pas différentiable en $(0, 0)$.